I Claim:

1. A microstructure, comprising:

a first finger including a length, a first surface and a second surface, said first finger capable of supporting a voltage potential between said first and second surfaces; and

a second finger capable of moving with respect to said first finger between said first and second surfaces upon application of a voltage to said second finger.

- A microstructure as recited in claim 1, further comprising a first voltage source for supplying a voltage to said first surface of said first finger.
- A microstructure as recited in claim 2, further comprising a second voltage source for supplying a voltage to said second surface of said first finger.
- A microstructure as recited in claim 3, further comprising a third voltage source for supplying a voltage to said second finger.

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5. A microstructure as recited in claim 4, wherein the magnitude

of said voltage supplied by said third voltage source is

significantly greater than said voltage supplied by said first

and second voltage sources.

6. A microstructure as recited in claim 4, wherein the magnitude

of said voltage supplied by said third voltage source is at least

ten times greater than said voltage supplied by said first and

second voltage sources.

7. A microstructure as recited in claim 4, wherein said

microstucture effects a force transducer upon said first finger.

8. A microstructure as recited in claim 4, wherein said

microstucture effects a force transducer upon said second

finger.

9. A microstructure as recited in claim 1, said microstructure

further comprising an output, said output connected to an

opamp circuit having an output, wherein said opamp circuit

output provides a signal representative of the relative position

between said first and second fingers.

10.A microactuator formed on a substantially planar substrate capable generating an electrostatic force in a direction said substrate, said

to substantially perpendicular

microactuator comprising:

a stationary comb-finger including a top portion

relatively distal from the substrate and a bottom

portion relatively proximal to the substrate, said

stationary comb-finger capable of supporting a

voltage potential between said top and bottom

portions; and

a movable comb-finger capable of moving with

respect to said stationary comb-finger between said

top and bottom portions upon application of a voltage

to said movable comb-finger.

11.A microactuator as recited in claim 10, further comprising at

least a first voltage source coupled between said top and

bottom portions of said stationary finger, and a second voltage

source coupled to said movable finger.

12.A microactuator as recited in claim 11, wherein the magnitude

of said voltage supplied by said second voltage source is

significantly greater than said voltage supplied by said at least

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first voltage source.

13.A microactuator as recited in claim 11, wherein said voltage

supplied by said second voltage source is approximately 100

volts and said voltage supplied by said at least first voltage

source is approximately 10 volts.

14.A comb-finger microactuator as recited in claim 10, a

dimension of said stationary finger in a direction perpendicular

to the substrate being greater than a dimension of said

movable finger in a direction perpendicular to the substrate.

15.A microactuator as recited in claim 10, a dimension of said

stationary finger in a direction perpendicular to the substrate

being at least one and one-half times greater than a

dimension of said movable finger in a direction perpendicular

to the substrate.

16.A comb-finger microactuator formed on a substantially planar

substrate capable generating an electrostatic force in a

direction substantially perpendicular to said substrate, the

comb-finger microactuator comprising:

a stationary comb-finger including an upper surface

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lying in a plane substantially parallel to said substrate;

and

a movable comb-finger including an upper surface

lying in said plane in an unbiased position, said

movable comb-finger capable of moving with respect

to said stationary comb-finger in a plane substantially

perpendicular to said substrate upon application of at

least a first voltage to said stationary comb-finger and

a second voltage to said movable comb-finger.

17.A microsensor formed on a substantially planar substrate

comprising:

a stationary finger including a top portion and a

bottom portion, said stationary finger capable of

supporting a voltage potential between said top and

bottom portions;

a movable finger capable of moving with respect to

said stationary finger between said top and bottom

portions;

at least one modulation voltage source connected

between said top and bottom portions of said

stationary finger; and

a circuit connected to said movable finger, said

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circuit including an output responsive to a change in

position between said movable and stationary fingers

18.A microsensor as recited in claim 17, wherein said circuit

includes an op-amp configured as a voltage buffer.

19.A microsensor as recited in claim 17, wherein said circuit

includes an op-amp and a charge integration capacitor,

wherein said circuit forms a charge integrator.

20.A microsensor as recited in claim 17, further including a

demodulation circuit.

21. A microsensor as recited in claim 20, further including a low-

pass filter.

22. A microsensor as recited in claim 20, wherein said modulation

voltage and demodulation circuit operate continuously.

23. A microsensor as recited in claim 20, wherein said modulation

voltage and demodulation circuit operate as a sampled-data

system.

24.A microsensor as recited in claim 17, further including at least one feedback voltage source coupled between said top and bottom portions of said stationary comb-finger.

25. A microsensor as recited in claim 17, wherein said output responsive to said change in position is frequency multiplexed.

26.A microsensor as recited in claim 17, wherein said output responsive to said change in position is time multiplexed.

27. An assembly for an optical switching array micromachined in a substrate, the assembly comprising:

a mirror for reflecting a signal to one of at least a first and second positions;

a spring member affixed to said mirror for flexibly anchoring said mirror over said substrate;

a microactuator for moving said mirror between said at least first and second position, said microactuator including:

a stationary comb-finger having a top portion relatively distal from the substrate and a bottom portion relatively proximal to the substrate, said stationary comb-finger capable of supporting a voltage potential between

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said top and bottom portions; and

a movable comb-finger attached to said mirror, said

movable comb-finger and said mirror moving with respect

to said substrate in a direction substantially perpendicular

to said substrate upon application of a voltage to said

movable comb-finger and said stationary comb-finger.

28. An assembly for an optical switching array as recited in claim

27, wherein said movable fingers are offset approximately

180° from said spring mechanism with respect to a center of

said mirror.

29. An assembly for an optical switching array as recited in claim

27, further including a second set of movable and stationary

fingers wherein said second set of movable and stationary

fingers are offset approximately 90° from the first set of

movable and stationary fingers.